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Substitute for form 1449A/PTO

INFORMATION DISCLOSURE STATEMENT BY APPLICANT

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Application No.	10/642,477	
Filing Date	August 15, 2003	
First Named Inventor	Masakazu Kawai	
Art Unit	3736	
Examiner Name	Jeffrey Gerben Hoekstra	
Attorney Docket Number	20911-08172	
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	-		U.S. PATE	ENT DOCUMENTS
		Document No.		
Examiner Initials*	Cite No.1	Number – Kind Code ² (if known)	Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document
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	A2	US-2006/0139355 A1	06-29-2006	Tak et al.
	А3	US-2006/0100818 A1	05-11-2006	Nakamura et al.
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/J.H./	A27	US-5,247,432	09-21-1993	Ueda

Examiner Signature	/Jeffrey Hoekstra/	Date Considered	05/21/2007

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	DIATIO	N DICC	OCUDE	Application No.	10/642,477
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				Art Unit	3736
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Sheet	7 2	of	2.	Attorney Docket Number	20911-08172

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Examiner Initials*	Cite No.1	Country Code ³ – Number ⁴ Kind Code ⁶ (if known)	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Τ ⁶
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Examiner Initials*	Cite No.1	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published	T⁰
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/J.H./	C2	ISAACS, P.M. et al., "Controlling Dynamic Simulation with Kinematic Constraints, Behavior Functions, and Inverse Dynamics," Computer Graphics, July 1987, pp. 215-224, Vol. 21, No. 4.	

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	STATEMENT BY	ADDITOANT	Filing Date	August 15, 2003	
	<i>,</i> → 1	APPLICANT	First Named Inventor	Masakazu Kawai	
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· '	\ 3		Examiner Name	Jeffrey Gerben Hoekstra	
Si	nee	of 2	Attorney Docket Number	20911-08172	ر

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		OTHER REFERENCES – NON-PATENT LITERATURE DOCUMENTS	
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/J.H./	C1	"Berkeley Researchers Developing Robotic Exoskeleton That Can Enhance Human Strength and Endurance, "ScienceDaily LLC, 1995-2004, [online] [Retrieved on October 9, 2006] Retrieved from the Internet <url:http: bleex.me.berkeley.edu="" bleexhistpdfs="" sciencedaily.pdf=""></url:http:>	
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				Art Unit	3736	
				Examiner Name	Jeffrey Gerben Hoekstra	
Sheet	2	of	2	Attorney Docket Number	20911-08172	

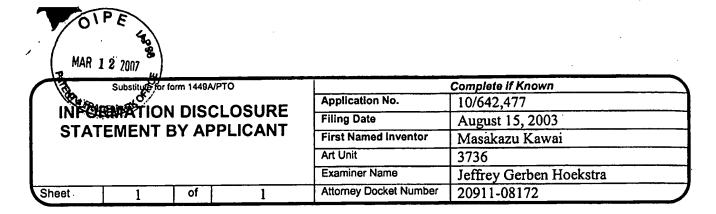
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/J.H./		Internet <url:http: ed_afo.html#dynamic="" education="" www.fillauer.com=""></url:http:>			
/J.H./	C6	PRATT, G.A. et al., "Active Orthotics for Helping the Neuromuscularly Impaired to Walk," [online] [Retrieved on October 9, 2006] Retrieved from the Internet <url:http: 9733740.1064791086.pdf="" grant="" materials="" www.vcl.uh.edu="" ~rcv03=""></url:http:>			
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/J.H./	A1	US-5,570,286	10-29-1996	Margolis et al.	

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Examiner Initials*	Cite No.1	Country Code ³ – Number ⁴ Kind Code ⁵ (if known)	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	T [€]
/J.H./	B1	WO 03/002054 A1	01-09-2003	Honda Giken Kogyo Kabushiki Kaisha	

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/J.H./	C1	International Search Report and Written Opinion, PCT/US06/22582, February 2, 2007, 8 pages.	
/J.H./	C2	WYETH, G.F. et al., "Distributed Digital Control of a Robot Arm," Proceedings of the Australian Conference on Robotics and Automation (ACRA 2000), pp. 217-222, August 30-September 1, 2000, [online] [Retrieved on December 31, 2006] Retrieved from the Internet <url:www.itee.uq.edu.au publications="" puma.pdf="" ~wyeth=""></url:www.itee.uq.edu.au>	

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